Ref #	· Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
S1	2	("4462046").PN.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/11/20 12:31
S2	1390	382/153,154.ccls.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/08/29 16:22
S3	172	382/153.cds.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/08/29 16:22
S4	1241	382/154.ccls.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/08/29 16:23
S5	23	S3 and S4	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/08/29 16:23
S6	2	("6101455").PN.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/08/30 11:35
S7	11	"6101455"	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/08/30 11:35
S8	13	("4238828" "4412121" "4639878" "4645348" "4672562" "4675502" "4753569" "4942539" "4979815" "5321353" "5329469" "5513276" "5666202").PN.	US-PGPUB; USPAT; USOCR	OR	OFF	2005/08/30 11:36
S9	9		US-PGPUB; USPAT; USOCR	OR	OFF	2005/08/30 13:03
S10	2	("5054299").PN.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/08/30 13:03
S11	1645	watanabe-atsushi.in.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/08/30 18:24

S12	202	watanabe-atsushi.in. and image	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/08/30 18:24
S13	112	watanabe-atsushi.in. and image and robot\$4	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2005/08/30 18:25
S14	2	("4611292").PN.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/02/28 16:31
S15	14905	(object\$2 or pattern\$2 or feature\$2 or template\$2 or ROI or (region near interest) or texture) and (match\$3 or compar\$4) and (("3" or three) near (D or dimension\$4)) and robot\$6	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/09/29 15:00
S16	694	(object\$2 or pattern\$2 or feature\$2 or template\$2 or ROI or (region near interest) or texture) and (match\$3 or compar\$4) and (("3" or three) near (D or dimension\$4)) and robot\$6 and (directions) same camera\$2	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/09/29 15:01
S17	. 8	("3804270" "3888362" "3986007" "4017721" "4146924" "4187051" "4271477" "4305130").PN.	US-PGPUB; USPAT; USOCR	OR	OFF	2006/09/29 15:10
S18	4	("3726591" "3783294" "4305095" "4506296").PN.	US-PGPUB; USPAT; USOCR	OR	OFF	2006/09/29 15:20
S19	6	("2674917" "2786096" "3796492" "4160263").PN.	US-PGPUB; USPAT; USOCR	OR	OFF	2006/09/29 15:25
S20	12	("4821206" "4831549" "4835710" "4851905" "4908951" "4969108" "5251156" "5255096" "5267143" "5297238" "5436542" "5576948").PN.	US-PGPUB; USPAT; USOCR	OR	OFF	2006/09/29 15:48
S21	4	("5153721" "5280542" "5446798" "5581665").PN.	US-PGPUB; USPAT; USOCR	OR	OFF	2006/09/29 15:56
S22	1435	pattern near7 match\$3 and parts and robot\$3	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/11/14 15:23
S23	1246	pattern near7 match\$3 and parts and robot\$3 and (recogniz\$5 or identif\$5)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/11/14 15:23

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S24	394	pattern near7 match\$3 same(recogniz\$5 or identif\$5) and parts and robot\$3	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/11/14 15:27
S25	39	pattern near7 match\$3 same(recogniz\$5 or identif\$5) same parts and robot\$3	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/11/16 18:32
S26	271	pattern near7 match\$3 and (recogniz\$5 or identif\$5) near9 (object\$3 or part\$1 or circuit\$3) and (robot\$6 same (sensor\$2 or camera\$2))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/11/16 18:35
S27	255	pattern near7 match\$3 and (recogniz\$5 or identif\$5) near9 (object\$3 or part\$1 or circuit\$3) and (robot\$6 same (sensor\$2 or camera\$2)) and (direction or orientation\$2)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/11/16 18:36
S28	46	manav near seth	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/11/20 13:55
S29	8743	382/103,115,141-160.ccls.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/11/20 13:55
S30	255	pattern near7 match\$3 and (recogniz\$5 or identif\$5) near9 (object\$3 or part\$1 or circuit\$3) and (robot\$6 same (sensor\$2 or camera\$2)) and (direction or orientation\$2)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/11/20 13:56
S31	434	pattern near7 (match\$3 or compar\$4 or correlat\$4) and (recogniz\$5 or identif\$5) near9 (object\$3 or part\$1 or circuit\$3) and (robot\$6 same (sensor\$2 or camera\$2)) and (direction or orientation\$2)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/11/20 13:58
S32	63	S29 and S31	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/11/20 14:09
S33	1507	901/3,46,47.ccls.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/11/20 14:09

624		C20 and C22	LIC DCOLID	OB	OFF	2006/11/20 14:40
S34	6	S30 and S33	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/11/20 14:49
S35	6702	700/57-64,95-99,110,159-163,245-260.ccls.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/11/20 14:46
S36	36	S30 and S35	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; .IBM_TDB	OR	OFF	2006/11/20 14:54
S37	19	S31 and S33	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/11/20 14:49
S38	66	S31 and S35	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/11/20 14:57
S39	1868	watanabe near atsushi	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/11/20 14:58
S40	1833	watanabe-atsushi.in.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/11/20 14:57
S41	246	watanabe near atsushi and image\$2	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR .	OFF	2006/11/20 14:58
S42	138	watanabe near atsushi and image\$2 and robot\$6	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/11/20 15:08
S43	32	taro near arimatsu and image\$2 and robot\$6	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	OFF _	2006/11/20 15:08

S44	61	taro near arimatsu	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM TDB	OR	OFF .	2006/11/20 15:25
S45	1	(teaching and model and shape and image and reference and direction).clm.	US-PGPUB	OR	OFF	2006/11/20 15:26